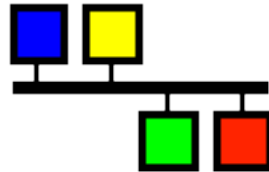


Experimental Physics and Industrial Control System

EPICS

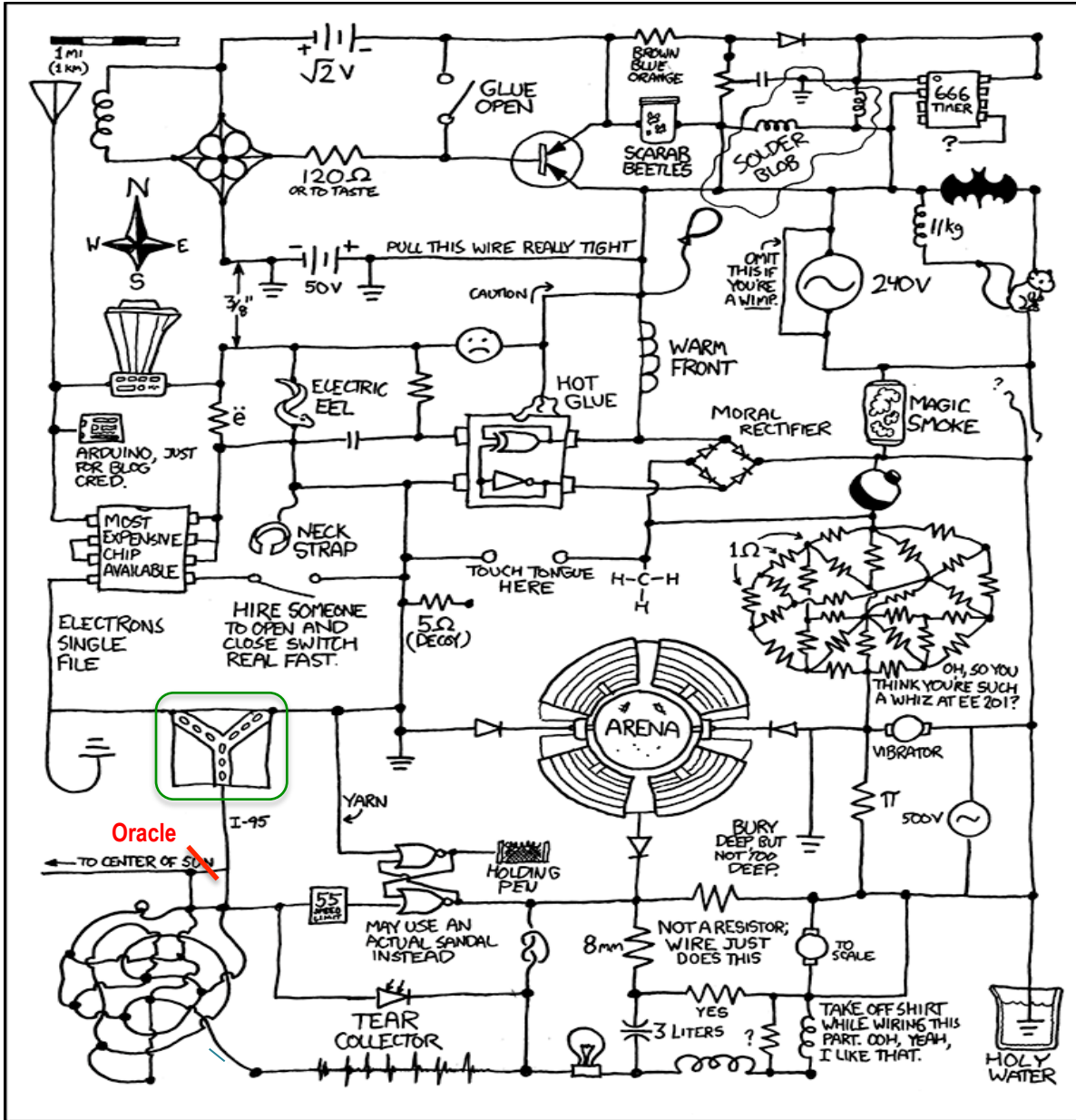


Kay Kasemir

kasemirk@ornl.gov

Sept. 2014

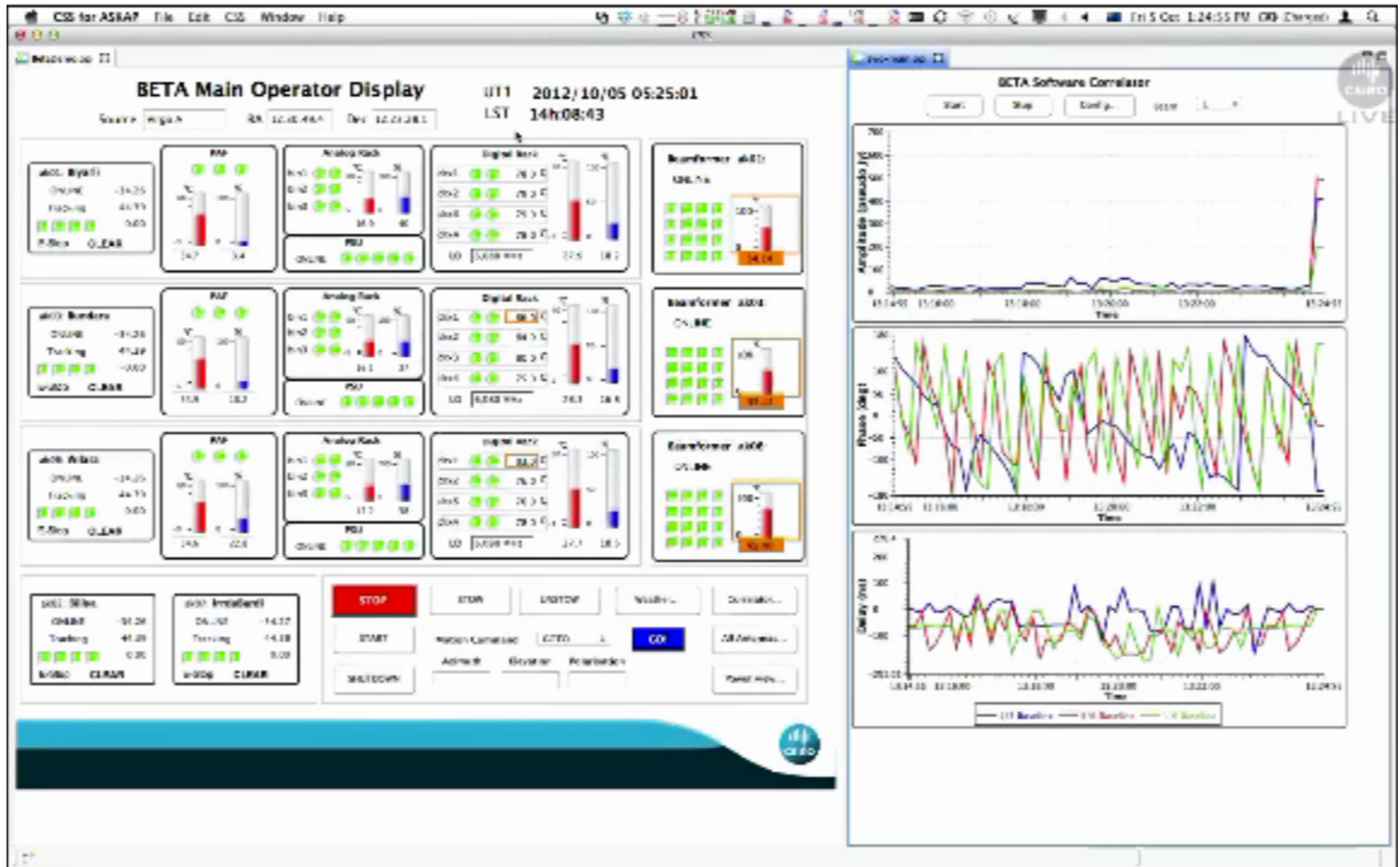
What EPICS looks like

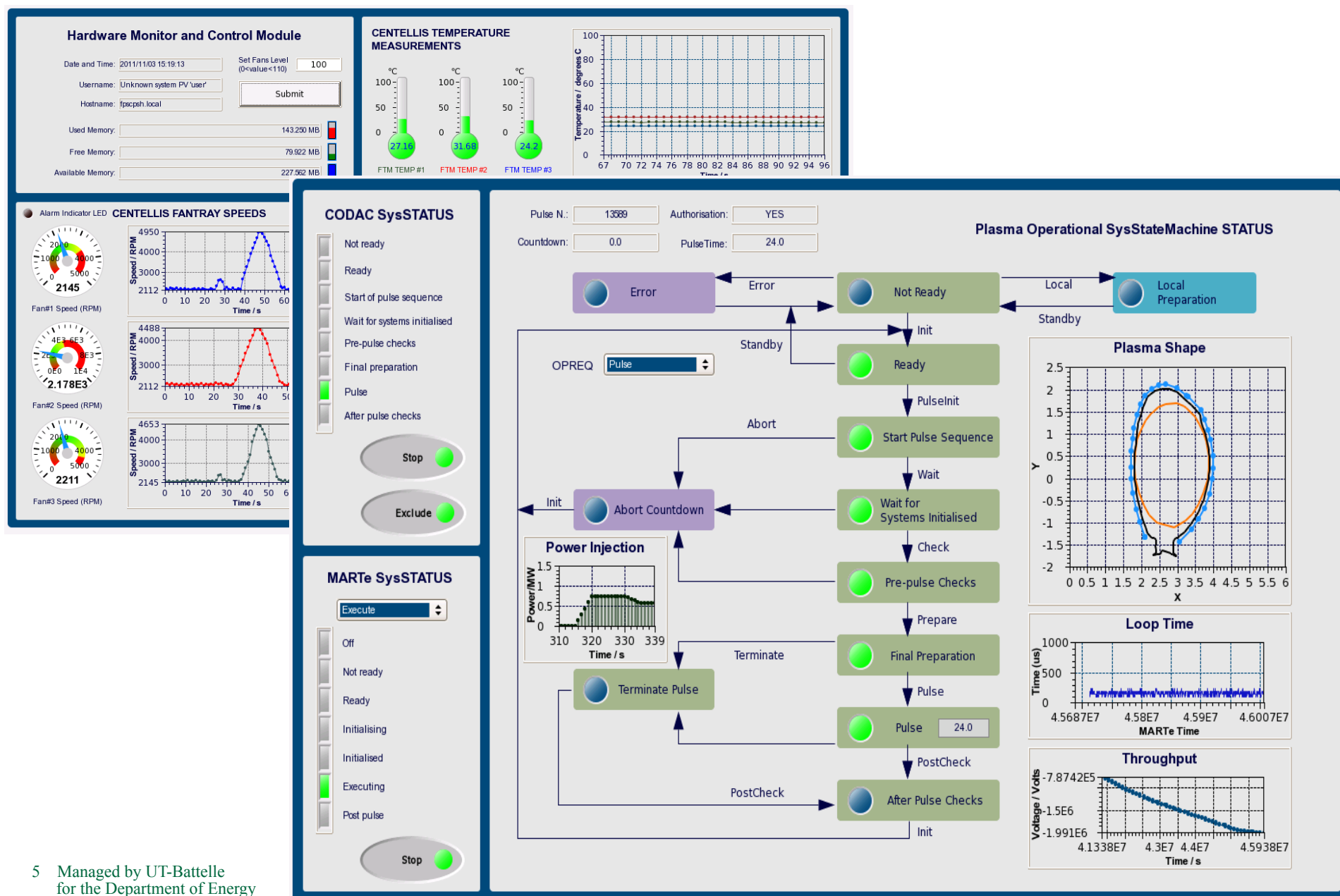


Australian Square Kilometre Array Pathfinder (ASKAP), Oct. 5, 2012



ASKAP User Interface





HFIR CG-1D

The screenshot displays the EPICS/CSS control interface for the HFIR CG-1D system. The interface is divided into several panels:

- Navigator:** Shows a file tree with directories like 'GIT_cg1d', 'T_share', '1d', 'data', 'DF', 'Tuesday', and 'Turbine_4_CT'. It lists numerous FITS files for turbine scans.
- Display:** Shows a camera image of a turbine component. The image is centered on a coordinate system with X and Y axes ranging from 0 to 2048.
- Camera Control:** Includes fields for Exposure Time (180.000), Binning (1), ADC Speed (1.00 MHz), Shutter Mode (Auto), and Camera State (Idle). There are Start and Stop buttons.
- Cooling:** Includes a Cooler status (On), Temperature (-60.00C), and Status (Stabilized at set pc).
- Advanced:** Includes buttons for Full Control (Simulated), Full Control (Andor), File I/O Configure, and General Camera.
- Motors:** A table showing motor positions and limits.

Motor	Readback	Position	Left/Move/Right	Limits
Lift Table	83.1 mm	83.1 mm	STOP	
Short Axis	80.0 mm	80.0 mm	STOP	
Long Axis	132.5 mm	132.5 mm	STOP	
Large Rotation T.	90.0 deg	90.0 deg	STOP	
Detector Table	225.0 mm	225.0 mm	STOP	Enabled
Small Rotation T.	181.4 deg	181.4 deg	STOP	
Camera Vert.	70.0 mm	70.0 mm	STOP	
Robofocus	50	50	In Out	Cabinet...
- CT Scan:** Includes fields for Start (0), End (182), Step (0.650), Device (Large..), Exposure (180.000), Delay (0 sec), and Directory (/home/controls/cg1d/data). There is a Go button and a Status section showing Angle (90.0 deg) and Scan Active.
- Console:** Shows a log of scan operations.

ID	Created	Name	State	%	Runtime	Finish	Command	Error
153	2013-01-08 17:54:24	Rotation Scan: Turbine_CT	Finished - OK		14:35:06	08:29:31	- end -	
152	2013-01-08 17:38:07	Rotation Scan: Turbine_CT_test	Finished - OK		00:15:35	17:53:42	- end -	

EPICS is not...

One product that you

- Install
- Run
- Done!

EPICS is a Collaboration

- **~1989: Started between**
 - LANL Ground Test Accelerator
 - ANL Advanced Photon Source
- **Until 2004: License agreement required**
 - LANL registered >150
- **Now:**
 - SNS, ANL/APS, SLAC, LANL, JLAB/CEBAF, LBNL, Fermilab D0, Keck & Gemini Telescopes ... in the USA
 - Canadian Light Source; DESY, BESSY, .. in Germany; PSI/SLS in Switzerland; Ganil, SACLAY in France; Diamond light source in England; KEK-K, J-Parc in Japan; IHEP in China; NSRRC in Taiwan; PLS in South Korea; Australian Synchrotron, ...
- **Yearly collaboration meetings**
 - One each in US and elsewhere
 - 100+ people attended in 2004, 05, 06.
- **'Tech-Talk' email reflector usually provides responses within a few hours**
 - <http://www.aps.anl.gov/epics>

EPICS Meetings

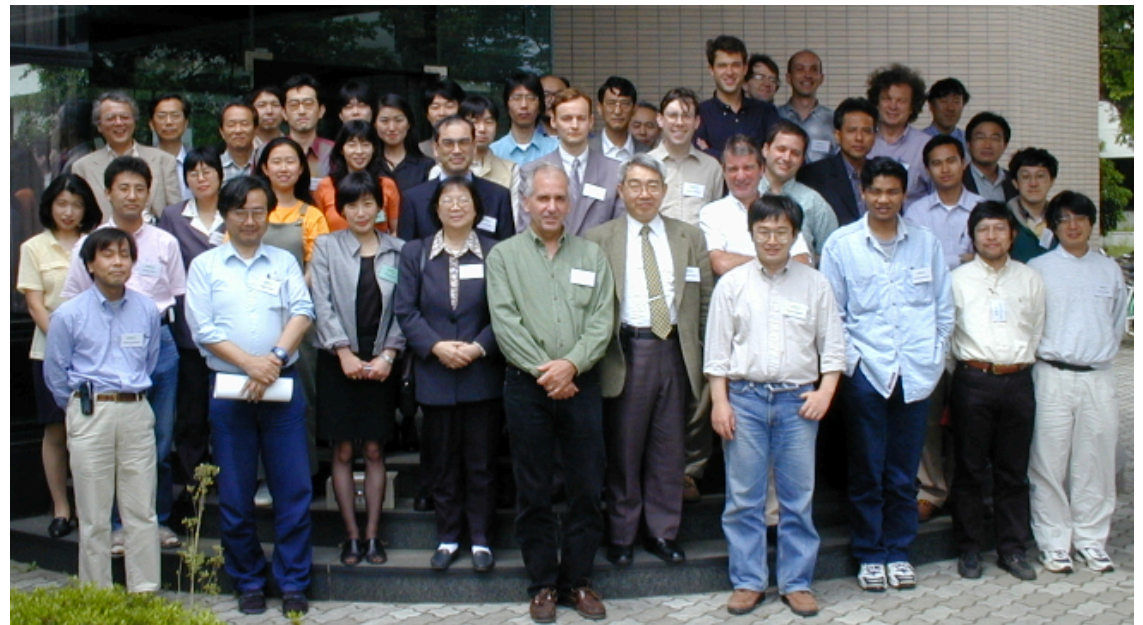
Pohang, 2013

Santa Fe 2004



Tzukuba, 2000

Berlin, 1998



EPICS is a Toolkit

... for distributed control systems.

- **Front-end: “Input/Output Controller” (IOC)**
- **Protocol: Channel Access**
- **Clients: Operator displays, alarm system, ...**

- **Mostly Portable: vxWorks, RTEMS, Linux, OS X, Windows**

Distributed

- Operator interface



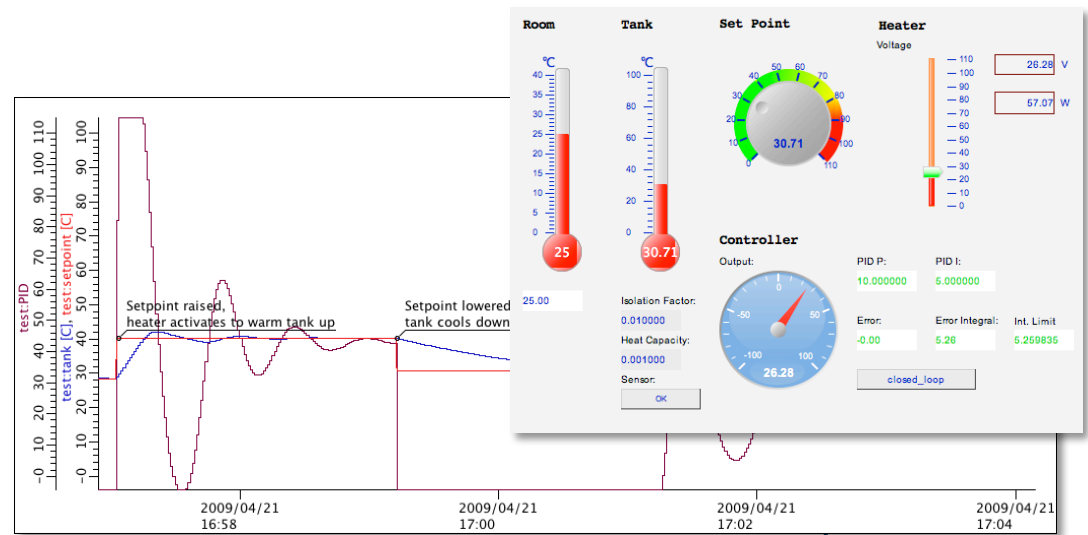
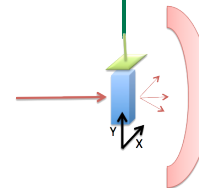
- Services: Archive, ...



- Front-end IOCs



- I/O, PLCs, ..



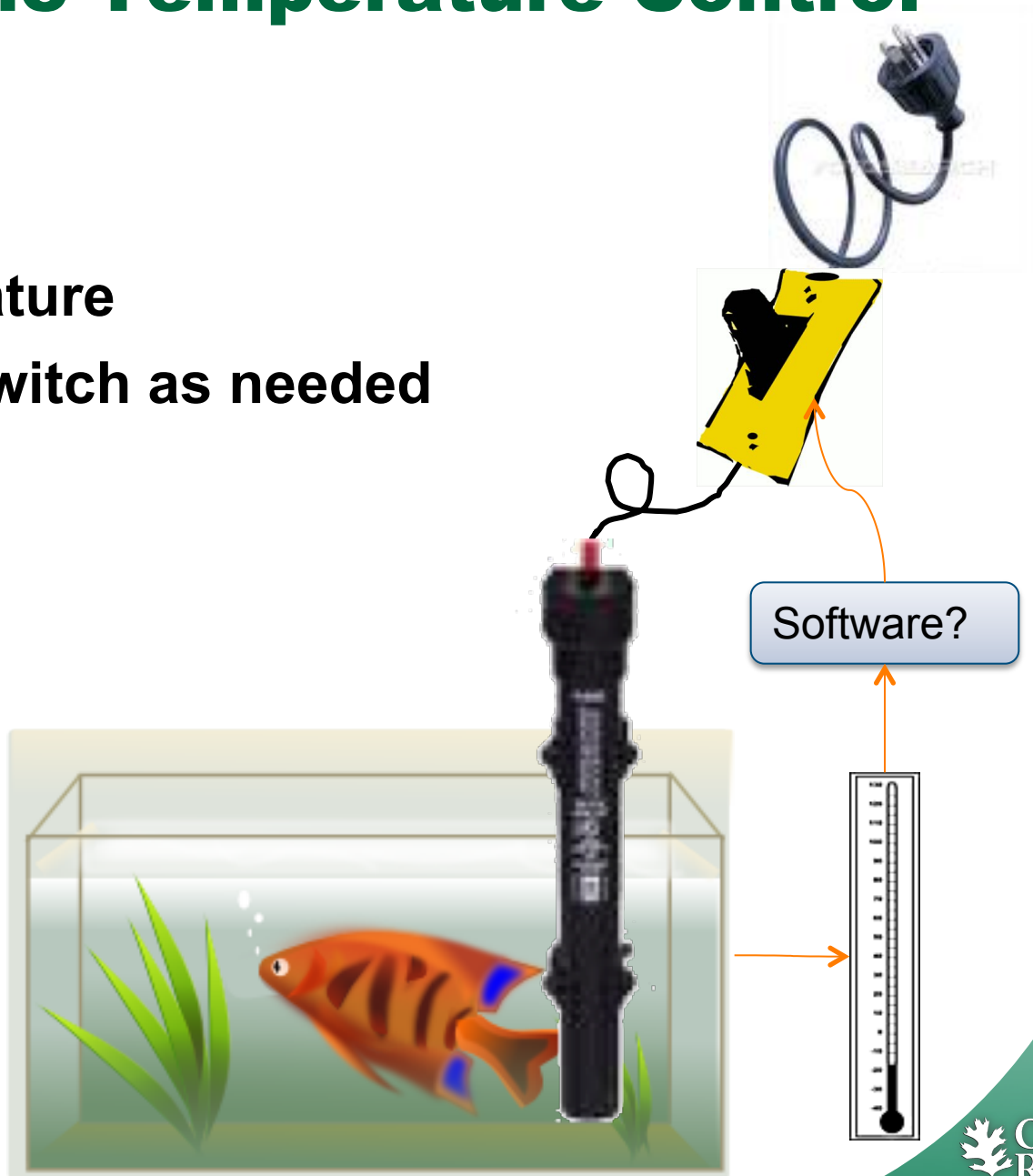
What an IOC does

- **Runtime ‘Database’**
 - Executes records
- **Known set of ‘Records’**
 - Read analog value
 - Write analog value
 - Perform computation
 - Control motor
- **Configuration**
 - SCAN=1 second
 - INP=..what to read..
- **Serve all via Channel Access**

Example: Basic Temperature Control

Task:

1. Read temperature
2. Open/close switch as needed
3. Repeat



Simplistic Code

```
Sensor temp = connectToSensor (...);
```

```
Switch switch = connectToSwitch (...);
```

```
Loop:
```

```
    if (temp.value() < 25)
```

```
        switch.close();
```

```
    else
```

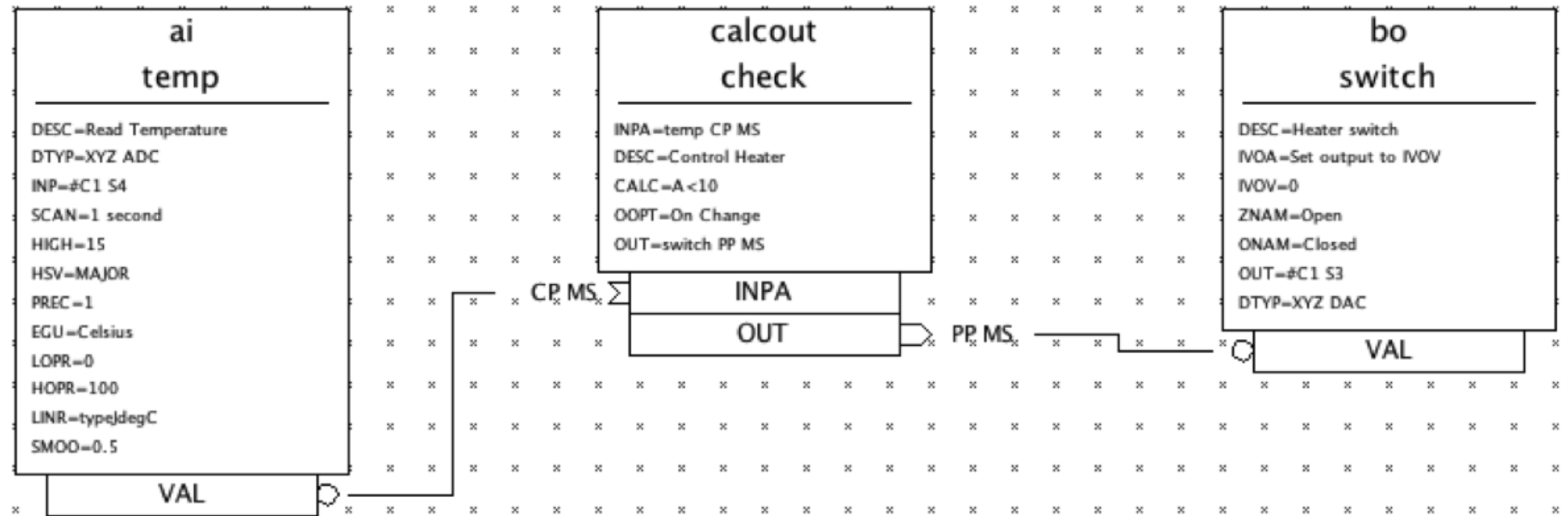
```
        switch.open();
```

```
    sleep(1.0);
```

What we omitted

- **Error** checking
- Code **comments**
- Apply some **smoothing** to the temperature reading to filter noise.
- Send current temperature and switch state to **network** clients (**operator display**). With **units**.
- Attach a **time stamp** to the data, so that network clients can see for example when the switch was last opened.
- Send **alarm** when the temperature is too low or high.
- Allow **runtime changes** of the threshold from the remote operator interface.
- Allow runtime changes to the **scan rate**.
- Maybe allow runtime changes to the **device address**?
- What if we have more than one fishtank?

EPICS 'Database' for Fishtank



Takes getting used to, but handles what we omitted.

Some Detail on EPICS 'Records'

```
record(ai, temp) {  
  field(DESC, "Read Temperature")  
  field(SCAN, "1 second")  
  field(DTYP, "XYZ ADC")  
  field(INP, "#C1 S4")  
  field(PREC, "1")  
  field(LINR, "typeJdegC")  
  field(EGU, "Celsius")  
  field(HOPR, "100")  
  field(LOPR, "0")  
  field(SMOO, "0.5")  
  field(HIGH, "15")  
  field(HSV, "MAJOR")  
}
```

```
record(calcout, check) {  
  field(DESC, "Control Heater")  
  field(CALC, "A<10")  
  field(INPA, "temp CP MS")  
  field(OUT, "switch")  
  field(OOPT, "On Change")  
}
```

```
record(bo, switch) {  
  field(DESC, "Heater switch")  
  field(DTYP, "XYZ DAC")  
  field(OUT, "#C1 S3")  
  field(ZNAM, "Open")  
  field(ONAM, "Closed")  
  field(IVOA, "Set output to IVOV")  
  field(IVOV, "0")  
}
```

~~Programming~~ Configuration

- **"SCAN=1 second" instead of start thread, delay until next multiple of 1 second, lock required resources, ...**
- **"SMOO=0.5" configures the smoothing algorithm.**
- **Almost any field in any record is accessible via network at runtime**
 - **Change scan rate, smoothing, ...**

IOC Database

- A single record can handle the scanning, signal conditioning, alarming of a temperature, pressure, or similar analog reading.
- Combined with binary and computational records, it can express the **data flow** logic for a front-end computer
 - Avoiding the pitfalls of real-time, multithreaded and networked programming.
- Can have thousands of records in one IOC.
- kHz-rate processing with record chains is doable
 - Of course limited by CPU. Not 1000nds of kHz rate-records...

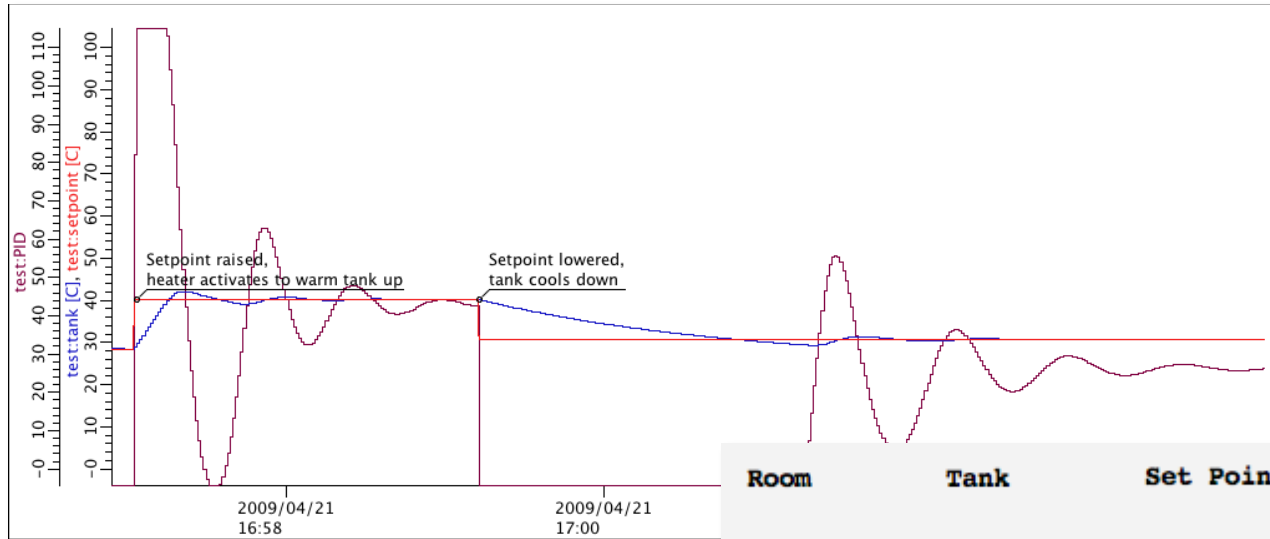
How fast?

- Can be fast or slow, it depends how you use it!
- Use the correct tool for the job; Database, custom code (IOC) or custom code (client)
- Ultimately speed depends upon hardware
- Some benchmarks*:

Machine	OS	CPU	Speed	Rec/sec	%CPU
MVME167	vxWorks	68040	33MHz	3,000	25
MVME2306	vxWorks	PPC604	300MHz	20,000	20
MVME5100	vxWorks	PPC750	450MHz	100,000	25
PC	Linux	PII	233MHz	10,000	27
PC	Linux	P4	2.4GHz	100,000	18

* Extrapolated from benchmark figures courtesy of Steve Hunt (PSI) and L.Hoff, (BNL)

Example Client: Operator Displays

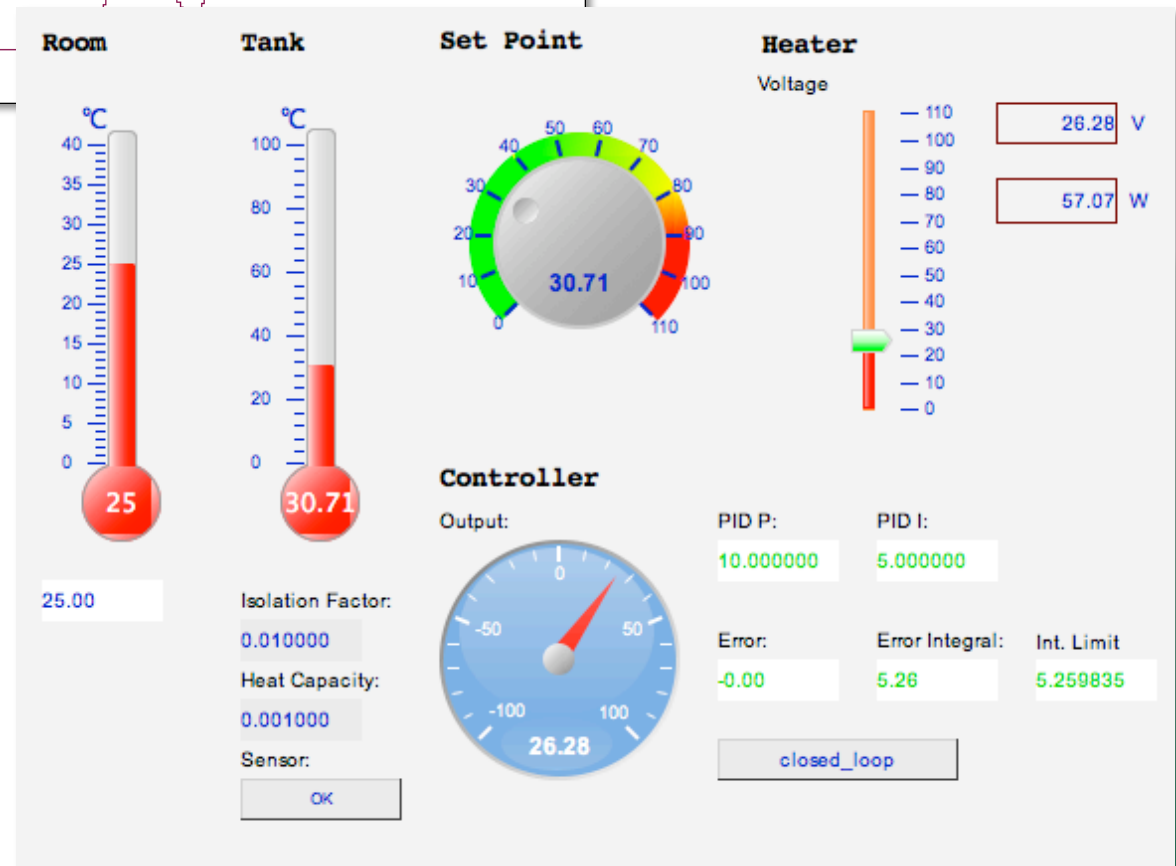


Created in Editor

- No coding
nor compilation

Networked

- Open/close
- Multiple OPIs



EPICS Vocabulary

- **EPICS Base**
Code for IOC, database support, basic records, channel access
- **IOC**
Input Output Controller, the front-end software
 - **Hard IOC**
Using real-time OS in VME crate
 - **Soft IOC**
IOC software running on Linux, ..., typically communicating with networked I/O
- **Database**
Executes the EPICS **Records**
- **Record**
EPICS processing block
- **Device** support
Code that connects records to hardware Driver
- **Driver**
Code that talks to hardware. May be unaware of EPICS
- **Channel Access**
EPICS network protocol. Exposes **Channels** aka **Process Variables**

EPICS Summary

- **Control System Toolkit**
 - Distributed, multi-platform, open source, extensible, ...
- **Not fancy, but “works”**
 - Accelerators,
Beam lines,
Telescopes,
Fusion experiments,
...

EPICS

